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Real Time Simulation of the Containment

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Abstract

Since the accidents at Three Mile Island and Chernobyl, more stringent requirements have been imposed on the containment system for full replica nuclear power plant simulators. The software model must be able to accurately respond under all normal operations and especially under abnormal conditions, including leaks and breaks of any size in any location in the Reactor Building.

A multiple node containment model, based on first engineering principles, was developed at CAE; it has already been successfully implemented on a number of simulators. An important feature of the model is its versatility. It is generic in that the techniques and methods used in the modelling can be easily implemented for any type of containment. It is also plant specific in that the nodalization is dictated by the physical structure, geometry, and dimensions of the reference plant. Thus, nodalization changes due to addition or removal of equipment or leaks can be done in a straightforward manner.

The techniques used to develop this model with all its features are presented in this paper. Typical transient results obtained for various LOCA's are included.

Introduction

The primary purpose of the containment is to minimize the uncontrollable release of radioactive materials to the environment. The Three Mile Island and Chernobyl incidents have increased awareness for the requirements for more sophisticated nuclear power plant simulators, capable of reliably reproducing containment response under all conditions.

Following consultations with the customers, a containment model was developed at CAE to provide the operators with maximum training values and to ensure that the criteria, discussed below, are achieved.

This model is versatile. It was originally developed for the containment of the St-Lucie simulator and has since been updated and implemented on the Davis-Besse, Crystal River, and San Onofre simulators. It is designed in a way that could easily be modified to fit the specific requirements of any containment for any type of power plant as dictated by the configuration, dimensions, and structures. The number of control volumes and configuration required to correctly duplicate the actual containment response and the proper temperature and radiation stratifications is easily incorporated. Moreover, this model was developed with the end user in mind, it is structured in a systematic manner, thus making it easy to maintain and modify.

Most importantly, the model is reliable in reproducing containment response under all normal and abnormal conditions. Reliability is achieved through the application of first principles. This means that mass balances are performed for each component in each vapour space control volume; energy balances are performed in each vapour space control volume for condensibles and for noncondensibles; and conservation of momentum is used to determine the flow rates between vapour space control volumes. The model is able to faithfully reproduce the various phenomena which might occur in the containment. These phenomena include flashing rates of all possible leaks, evaporation from the liquid spaces, and condensation in the coolers, on the walls, due to rain out (inability of the air to support any more water vapour), and due to the operation of the containment sprays.

Model Nodalization

The nodalization is plant specific in that the number of control volumes and their locations depend on the physical structure and restrictions, the equipment and their locations, and the anticipated flow paths. A typical PWR containment is shown in figure 1; this containment is divided into 5 control volumes (CV's) as presented in figure 2: CV-1 covers the area around the reactor vessel inside the primary shield, CV-2 covers the dome area inside the containment, CV-3 and CV-4 present the steam generators compartments, and finally CV-5 covers the annular space between the secondary shield and the containment walls. Figure 3 shows the corresponding nodal diagram and the possible flow paths within the containment.

Figure 1: Typical PWR Containment



Figure 2: Containment Control Volumes I

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Conservation of Component Mass

A mass balance is performed for each component (nitrogen, oxygen, hydrogen, and water vapour) in each vapour space CV taking into account all possible flows, including flows between the CV's, and leaks and breaks into the containment.

Consider a vapour space CV "k" with neighbouring CV's "j" and "l". The component mass "i" in CV "k" can be described by the mass balance equation:

$$\frac{dM_{ki}}{di} = \sum W_{jk} X_{ji} + \sum W_{jk}^{i} X_{ji}^{i} - \sum W_{ki} X_{ki} - \sum W_{ki}^{i} X_{ki}^{i}(1)$$

where,

- MEi Mass of component i in CV k
- W_{jk} Internal mass flow rate from CV j to k
- X_{ii} Mass fraction of component i in internal CV i
- W_{ik} Mass flow rate from external CV j to internal CV k
- X_{ii} Mass fraction of component i in external CV j
- W_{kl} Internal mass flow rate from CV k to l
- Xki Mass fraction of component i in internal CV k
- W., Mass flow rate from internal CV k to external CV 1

By defining,

$$X_{ji} = \frac{M_{ji}}{M_j} \tag{2}$$

where.

Mii Mass of component i in CV j $M_{\rm f}$ Total mass in CV j

then substituting the expression for X_{ji} in equation (1), and using backwards differences, the conservation of mass equation is given in matrix form by:

$$AM_{ki} = S_{ki} \tag{3}$$

where.

A Mass matrix

Source vector SH

Conservation of Energy

The conservation of energy equation is applied separately for the condensibles (water vapour) and for the noncondensibles (nitrogen, oxygen, and hydrogen combined) for each CV and is consistent with

the component mass balances; the noncondensible gases are assumed to be in thermal equilibrium. Since the time constant of the enthalpy response is always greater than the module iteration rate, the equations may be solved sequentially without affecting the transient response. The energy balance takes into account all the relevant inflows and their enthalpies, as well as the heat flux and heat exchange with energy sources and heat sinks. Taking backwards differences, the energy balance equation for component "r" in CV "k", where "r" represents either condensibles or noncondensibles, can then be implicitly integrated as:

$$h_{kr} = \frac{h'_{kr}M_{kr} + dt(\sum W_{jk}X_{jr}h_{jr} + \sum W'_{jk}X'_{jr}h'_{jr} + Q_{kr})}{M_{kr} + dt(\sum W_{jk}X_{jr} + \sum W'_{jk}X'_{jr})}$$
(4)

where.

- M_{kr} Mass of component r in CV k
- Specific enthalpy of component r in inher ternal CV k Value of h_{kr} from previous iteration
- h'_{kr}
- X_{jr} Mass fraction of component r in internal CV j
- hjr Specific enthalpy of component r in internal CV j
- X_{jr}^{*} Mass fraction of component r in external CV j
- h, Specific enthalpy of component r in external CV j
- Q_{kr} Heat transferred to component r in CV k from external heat sources and sinks. e.g. reactor vessel, walls, coolers, heaters, etc.

Temperature and Pressure Calculation

Having determined the masses and energies in the various CV's, the state of each CV can be found (assuming perfect mixing in each CV).

The enthalpy of the gas/water-vapour mixture is calculated based on the Gibbs-Dalton law (Wark 1983) which states that the mixture enthalpy is simply the sum of the enthalpies of the individual components.

By using the definition of heat capacity at constant pressure which relates temperature to enthalpy and using the partial pressure of vapour to evaluate the saturation conditions, the temperature of each CV is calculated.

$$\Gamma_{b} = \frac{A_{mis} - [h_{d}(P_{bv}) - Cp_{bv} * T_{set}(P_{bv})] * X_{bv} - h_{ref} * \sum X_{bnei}}{(X_{bv} * Cp_{bv}) + Cp_{bne} * \sum X_{bnei}}$$
(5)

where,

T_k	Mixture temperature in CV k
h _{mix}	Mixture enthalpy in CV k
$h_g(P_{kv})$	Saturation enthalpy at the partial pressure of vapour in CV k
Tsat(Pkv)	Saturation temperature at the partial pressure of vapour in CV
Xku	Mass fraction of water vapour in
X _{knci}	Mass fraction of noncondensible
	component i in CV k
h _{ref}	Reference enthalpy evaluated at reference temperature $T_{ref} = 0$
$C p_{kv}$	Specific heat of vapour in CV k
Cpknc	Specific heat of noncondensibles (assumed to be nitrogen) in CV k

Having determined the temperature, the partial pressures of the various components in each CV are computed. For the noncondensibles, the partial pressures are calculated from the perfect gas law (Wark 1983); whereas, the partial pressure of the vapour is calculated as a function of density and temperature. The total pressure in each CV is then calculated simply as the sum of the partial pressures of the individual components. Therefore,

$$P_{k} = \frac{R(T_{k}+C)}{V_{k}} \sum \frac{M_{knci}}{M_{wnci}} + P_{kv}(M_{kv}, V_{k}, T_{k})$$
(6)

where,

 P_k Total pressure in CV k

$$P_{kv}$$
 Partial pressure of vapour in CV

 T_k Mixture temperature in CV k

 V_k Total volume of CV k

 M_{kv} Mass of vapour in CV k

$$M_{knci}$$
 Mass of noncondensible compo-
nent i in CV k

Mwnci Molecular weight of non condensible component i

R Universal gas constant

C DegF to DegR (DegC to DegK) Conversion Factor

Conservation of Momentum

The mass flow rate of the mixture between the internal CV's is obtained from the conservation of momentum equation. Natural recirculation within the containment is induced by the variation in density between the CV's, while forced recirculation is calculated based on the difference in pressures between the CV's and the no-load pressures of the fans. Combining the two flows yields,

$$W_{jk} = A_{jk}(P_j + Pnl_{jk} - P_k + (\rho_j z_j - \rho_k z_k) * g)$$
(7)

where,

Ajt	Admittance of link j-k
P_j	Pressure in CV j
Pnljk	No-load pressure of the fans on
Ŧ	link j-k
P_k	Pressure in CV k
Pi	Density in CV j
PE	Density in CV k
Z;	Elevation of CV j
z <u>k</u>	Elevation of CV k
a	Acceleration due to gravity

Flashing, Evaporation and Condensation

The flashing of all leaks inside the primary containment is determined by comparing the enthalpy of the leak flow to the saturation conditions present in the containment. The saturation conditions are evaluated at the partial pressure of the vapour.

$$W_f = \frac{h_l - h_f}{h_{fg}} * W_l \tag{8}$$

where,

- W_f Flashing flow
- h_l Specific enthalpy of leak flow
- h_f Saturated liquid specific enthalpy of containment vapour
- h_{fg} Latent heat of containment vapour

W₁ Leak flow rate

Evaporation from the liquid CV's (sumps, containment floor) is evaluated based on the difference between the saturation pressure of the liquid evaluated at the temperature of the liquid CV and the partial pressure of the vapour in the vapour space above the liquid.

All heat transfer between two mediums is calculated based on the Fourier equation (Holman 1981):

$$Q = U(T_a - T_b) \tag{9}$$

where,

- Q Heat transfer
- U Overall heat transfer coefficient
- T. Temperature of medium a
- $T_{\mathbf{k}}$ Temperature of medium b

The condensation rate is determined by calculating the heat transfer from the condensible fluid at the saturation temperature to the cooling medium. The condensation rate is then given by:

$$W_c = \frac{Q_l}{h_{fg}} \tag{10}$$

where,

 W_c Condensation flow rate

Latent heat transfer Qr

Another type of condensation, which is called rain out, is considered when the containment space becomes saturated and can no longer support the amount of vapour present in the atmosphere. The condensation rate is given by

$$W_r = M_{kv} * (1 - X_k) * Cr$$
(11)

where.

- W_r Condensation flow rate due to rain out
- Xı Quality of vapour in CV k

CrRain out constant

Radiation

Apart from the mass components in the CV's that contribute to the total pressure calculations, radioactive species are transported in the vapour space as mass fractions. Different species are transported by different mediums. Since noble gases are not expected to condense into the liquid CV's to any extent, they are transported in the noncondensibles. Other species such as iodine, however, are expected to follow the condensing water vapour into the liquid spaces and also to evaporate from the liquid spaces. These species are transported in the condensibles. The activity equation can be written in a similar manner to the enthalpy equation as follows:

$$A_{kq} = \frac{A'_{kq}M_{kq} + dt(\sum W_{jk}A_{jq} + \sum W'_{jk}A_{jq})}{M_{kq} + dt(\sum W_{jk} + \sum W'_{jk} + L_qM_{kq})}$$
(12)

where,

- Mke Mass of species q in CV k
- Specific activity of species q in internal Akq CV kValue of A_{kq} from previous iteration
- A'ka
- Specific activity of species q in internal Aję CV j internal CV to k
- Specific activity of species q in exter-A, nal CV j

 $L_{\mathbf{f}}$ Decay constant of species q

Liquid Control Volumes

The hydraulic masses in the liquid CV are determined using conservation of mass:

$$M_l = M'_l + dt \left(\sum W_i - \sum W_o\right) \qquad (13)$$

where.

- M Mass of liquid
- M_1' Value of M_l from previous iteration
- W_i Flow into liquid CV
- W, Flow out of liquid CV

Note that the evaporation and condensation to and from the vapour space CV's are accounted for in the outflow and inflow terms of the above equation.

Enthalpy of the liquid CV's is calculated from an energy balance.

Test results

Some representative test results will now be presented to indicate the effective implementation of the model on the Crystal River Unit 3 Training Simulator. Test results for a large LOCA (full line break) will be displayed and discussed. These results will then be compared to the expected results obtained from the Final Safety Analysis Reports. Finally test results for a small LOCA will also be displayed and discussed.

A. Large LOCA

Figure 4A shows the containment response during a large LOCA (full line break) as given by the Final Safety Analysis Reports for the Crystal River Nuclear Power Station. The figure shows a plot of containment average pressure versus time after rupture.

The figure indicates that a peak containment pressure of approximately 49 psig (64 psia) is reached in slightly less than 20 seconds following the initiation of the LOCA. The value of this initial pressure peak depends on the amount of energy that is provided from the reactor coolant system (RCS) and the amount of energy that is transferred through the walls (condensation on the walls). Following a slight decrease in the containment pressure (3 psi), due to the action of the coolers, sprays, and the walls, a second rise in pressure occurs (49 psig). This second rise is a consequence of additional energy inputs from RCS. After the containment pressure peaks for the second time, the containment pressure will once more decrease slowly due to the actions of the coolers, sprays, and the walls.

Figure 4B shows the test results obtained after a large LOCA accident was initiated on the Crystal River simulator. The figure shows plots of average temperature, pressure, as well as liquid and vapour leak flows. A time frame of 5 minutes was chosen for this test. Note that the pressure versus time plot from the Final Safety Analysis Reports, converted to a linear scale, has been superimposed on figure 4B for comparison with the simulator results.

The test results show an initial pressure peak of 47 psig which is reached in less than 25 seconds from the initial LOCA. In the model, the proper pressure peak is achieved by tuning the overall heat transfer coefficient for the walls, which influences the amount of heat that is transferred through the walls. The initial peak is then followed by a brief period where the containment pressure decreases slightly (2 psi) until a second pressure peak occurs (48 psig). Following the second pressure peak, the containment pressure decays slowly due to the action of the sprays and coolers and walls.

The results show the successful implementation of first principles to correctly determine the pressure and temperature response in the containment following a large LOCA. This is clearly indicated by the close agreement between the test results, obtained from the Crystal River simulator, and the results given by the Final Safety Analysis Reports.



B. Small LOCA

Figure 5 displays the containment response during a small LOCA for the Crystal River simulator. The figure shows plots of average pressure, temperature, liquid and vapour leak flows versus time. A time frame of 10 minutes was chosen for this test.

During a small LOCA, the containment pressure does not climb to the values witnessed during a large LOCA. Consequently the containment average pressure does not reach the levels required to initiate the spray system. Therefore the only means available to decrease the containment temperature and pressure are the walls and the coolers.

Figure 5 shows the initial increase in pressure until a maximum value of approximately 40 psia is attained. Following this initial increase the containment pressure and temperature decrease slowly as a result of heat losses through the walls and the action of the coolers. Throughout the test, the pressure and temperature occasionally spike up. This is a result of intermittent bursts of energy from RCS into containment.

Figure 5: Small LOCA Test Results - Crystal River Simulator



(C) LOCA Hot Leg Vapour Flow (-1000 - \$0000 Lbm/s)

(D) LOCA Hot Leg Liquid Flow (0 - 90000 Lbm/s)

Conclusion

A multiple node containment model was developed and proven to be successfully implemented on a number of simulators. The model was shown to be reliable in reproducing the proper containment responses during a wide range of transients. This is attributed to the application of first principles. In addition the test results indicate that evaporation from liquid spaces, flashing of leaks, condensation in coolers, on the walls, due to rain out, and due to the operation of the containment sprays are all reproduced faithfully.

The model is versatile. The techniques and methods used in developing this model can easily be implemented for any type of containment. The model is tailored to the specific requirements of the plant. The number of CV's and their location depend on the physical structures and restrictions, the equipment and their location, and the anticipated flow paths.

Finally, the model is easy to maintain and modify. This is due to the systematic approach used in its structure and minimum effort required to fine tune the model to provide the required responses.

Acknowledgements

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Real Time Simulation of the Release and Transport of Radioactive Contaminants

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ABSTRACT

Calculating the responses of the radiation monitoring system (RMS) remains one of the most difficult aspects of nuclear power plant simulation to bring into the post-TMI, first principles simulator era. This task requires the simulation of the transport of radioactive contaminants, the transport of the radiation itself, and the instrument channel including the detector. The complex physics and lack of knowledge of input parameters have made these models lag the general simulator trend away from logical/heuristic modeling of physical systems. This paper describes a series of advances to the modeling methodology to change this situation.

The objective in the design of this model was to always calculate qualitatively reasonable radiation detector readings. This is the best that can be supported by the current level of scientific understanding of the phenomena involved. In particular, "the state-of-the-art of... (non-real-time research codes)... are accurate only within a factor of 100 even if all the accident conditions are known." (McKenna 1988). A secondary goal of the model design was to produce a real time model which includes all the important phenomena such that there would be no motivation to change the model until there is significant progress in the research code modeling in this field.

The purpose of the model is to allow realistic training of operators on the RMS responses. RMS

is of major importance in the identification of the state of a nuclear power plant during many acc dents. For operators to develop the skills needed to use this information, they need a simulator that includes the phenomena that caused "the radiatio monitors during the TMI accident...(to be) more a source of 'puzzlement than of enlightenment'" (McKenna 1988).

MODEL SUMMARY

The model is divided into a fuel failure model, a transport model, and a detector model.

The fuel failure model consists of a mechanic ic fuel failure calculation and a CINDER (England 1962) type calculation of the fission product in the tory available to be released.

The transport model is a very fine mesh model, the ically one radioactive contaminant node for every fluid model node. Transport is based on groups of isotopes which belong to the major chemical classes of radioactive contaminants of importance to Laclear power plants (noble gas, halogen, particulate, and N-16). A decentralized model is used, i.e., the transport calculations are performed in the simulator fluid model subroutines. A modularized approach to the transport equations allows the contaminant transport to be added as a separate module into an existing block structured model builder for fluid systems. Separate code fragments are into duced for rooms, for tanks, and for pipes. Tatlk nodes primarily allow partitioning of the various chemical classes between liquid and gas phases. Room nodes differ from tank nodes in that they allow the transport of aerosols and the plating out of contaminants on the walls of the room. The pipe nodes only transport. Phase change is not allowed within pipe nodes.

The detector model sums the contributions from the various sources of radiation, calculates its effect on the detector responses, and models the instrument channel. Sources include shine from possibly contaminated pipes and tanks, the "nameplate" radiation source, radiation carried in the room air, shine from normal operation radiation (such as gamma radiation from the N-16 in the primary coolant), radiation from materials which have plated out on the walls of rooms and equipment, direct gamma shine from the reactor, and the radiation from check sources and live zero sources. Shine is a somewhat unscientific term which refers to gamma radiation from "unexpected" sources. The "nameplate" radiation source is the process stream for which the detector was installed to monitor. Detector saturation, filter paper delay times, and statistical noise are all treated in this model.

Fuel Failure Model

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The fuel failure mechanisms modeled are clad stress greater than the clad stress limit, clad strain greater than the clad strain limit, and the zirc-water reaction. Pellet cladding interaction (PCI) failures are currently only modeled as an instructor selected malfunction. The model requires a companion fuel rod model which calculates clad temperatures, fuel rod internal pressure, fuel pellet temperatures, and reactor core internal pressure. The zirc-water reaction thins the fuel rod cladding and contributes heat to the cladding temperature calculation in the fuel rod model. Fuel rod power census data from nuclear design code calculations are used to estimate detailed, rod by rod, power and temperature distributions where needed.

The power history effect on the nuclides available

to be discharged to the coolant (the gap inventory) is calculated via a very simplified model of the diffusion of the fission products from the fuel pellet, but a fairly complete treatment of the radioactive decay chains. A CINDER-like calculation, with terms for the important fission product sources, their half lives, and their daughter products is performed in order to calculate the relative gap inventory of the different groups of isotopes modeled.

Transport Model

Four classes of radioactive isotopes are transported. Class 1 represents the halogens, transported primarily in the liquid phase. Class 2 represents the noble gases, transported primarily in the gaseous phase. Class 3 represents the particulates, transmitted in the liquid phase (and as aerosols). Each of these first three classes may have two groups of isotopes, one representing the short half life isotopes in the class and one representing the longer lived isotopes in the class. Class 4 represents N-16 and is calculated only in those fluid models which may see appreciable amounts of N-16 (half life of 7.1 seconds).

There are three kinds of transport nodes: pipe nodes, room nodes, and tank nodes.

Pipe nodes only transport. Pipe nodes do, however, transport <u>all</u> the groups. With two groups of isotopes modeled for each class, there will be six (or seven with N-16) concentrations of radioactive contaminants being transported with the fluid. Thus even though the noble gases are primarily present in gas spaces, they are also transported with the liquid stream in appropriate amounts. This is necessary due to the tiny amounts of radioactive isotopes which are observable on nuclear power plant RMS instrumentation.

Tanks are two region nodes having both a gas and a liquid space. Separate concentrations of each group of contaminants are calculated for each space. Tank nodes partition groups between the gaseous phase and the liquid phase. The noble gases are partitioned based on Henry's law data, with temperature as the primary independent variable. The halogens are partitioned based on a system dependent constant set such that the halogens are predominantly concentrated in the liquid space. The particulates are partitioned entirely into the liquid phase save for those situations (such as a pipe leak into a room with flashing to steam) in which they are transported as aerosols.

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Rooms are different from tanks in that their surface area and volume are large as compared to the volume of water which may be expected to exist in the room. As such, the dominant mechanism is not the equilibrium between vapor and liquid spaces expected for tank nodes, but rather the processes of settling and plating out on the surfaces of the room.

For the case of a leak into a room, some of the water may flash into steam, depending on the enthalpy of the leaked fluid. The particulates associated with the mass of water which flashes to steam become an aerosol. The aerosol is modeled to gradually settle out of the room volume onto the room floor. Halogens are allowed to plate out onto all the surfaces of the room.

The model nodalization is determined in most cases by requiring a transport node for each fluid model node which may be isolated from other fluid model nodes. Exceptions include systems which cannot affect RMS detector readings. For instance, the model for the cooling water to the condenser may not need to include radiation transport.

In some models there are nodes which cannot be isolated one from another. For instance, the secondary side of a steam generator may typically have many nodes. These nodes would all be represented by a single tank model node in the tranport model. In general, nodes which cannot be isolated from one another and which can be considered as being relatively well mixed with o another are combined for radiation transport purposes.

Detector Model

Two aspects of this model are particularly impditant to training as they can generate somewhat unexpected detector response. One is the radition shine source to detectors which can cause d tector response in many cases from other than the "nameplate" radiation source. Second is detect saturation, a phenomenon which can lead to a du crease in observed count rates while the actual level of radiation is greatly increasing.

Radiation shine is calculated to all radiation detectors from both global and local sources of r diation. Shine is based on local shine from the systems in the immediate vicinity of the detector, plus global shine from systems which have the capability to be large sources of radiation that will appreciably affect the readings on nearly all the radiation monitors in the plant. These source shine to detectors based on the distance between the system and the detector and the attenuation, due to the structural materials between the deter tor and each system. Local shine is based on [) the identification of systems in the vicinity of, each detector which have the capability of appreciable shine to the detector and on 2) an estimate of the attenuation caused by the local geometryand intervening material involved.

Detector count rates are adjusted for the effects of detector dead time. Detectors which have the detection of a count rate as a fundamental aspect of their operation will always have a dead time. Paralyzable detectors have the characteristic that a second event which occurs during the dead time following an event extends the dead period. This is not true of non-paralyzable detectors. Detectors which collect a current to calculate an integrated quantity of radiation do not have dead time.

Generally, then, the detector dead time characteristics are modeled as follows: GM tubes are paralyzable, scintillation counters are nonparalyzable, and ion chambers do not have dead time. But the entire instrument channel must be simulated to include the effects of electronics which may have been added to preclude observable saturation.

Non-paralyzable detector count rates are calculated from the following equation (Tsoulfanidis 1983):

$$g = \frac{n}{(1.+n\tau)}$$

where

g is the observed count rate

n is the actual count rate

t is the detector dead time.

One feature of this equation is that non-paralyzable detectors saturate at high count rates at a value equal to the inverse dead time.

Paralyzable detector count rates are calculated from the following equation (Evans 1955):

$$g = n \times exp(-n\tau)$$

This equation shows that the observed count rate can decrease due to an increase in the real count for paralyzable detectors at high count rates. This effect has been observed on the detectors during steam generator tube rupture transients (Nuclear Power Experience, 1975).

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CURIE TRANSPORT MODEL MODIFICATION ON THI SIMULATOR

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ABSTRACT

The present TMI Curie Transport model consists of three portions: a source module, Primary side transport and BOP transport. The source module can be event-triggered or be triggered by high temperature and it consolidates all released radioactivities into four characteristic isotope groups. There are also four degrees of core damage and ten associated release categories which are determined by the Reactor Coolant System pressure and the in-core thermocouple tempera-The transport model is emtures. bedded in the RCS model which simulates the nuclide conservation, decay and transport in the primary system flow paths. It also determines the nuclide transport to other balance-of-plant systems such as Makeup or Decay Heat Removal System and the leakage of the nuclide into the secondary system in the event of steam generator tube Also, transport of the rupture. nuclide in the secondary system is performed and the concentrations are converted to dose rate or other appropriate units for panel display.

The testing results have indicated that the modified model is capable of simulating the actual release, transport and response of the Radiation Monitoring System for steady state and transient operations. In addition, the simulator has also demonstrated that it is consistent with the NUREG-0737 guideline for initial estimate of the degree of core damage for severe accidents and the dose assessment calculations of the plant emergency preparedness model.

1. INTRODUCTION

In order to protect the public and the plant personnel against possible plant contamination, it is necessary to provide the monitoring of radiation levels in and around a nuclear power plant by placing radiation detecting devices in various vital areas. Naturally, the training for the proper operation of the Radiation Monitoring System (RMS) is imperative to the safety of the plant personnel as well as the safety of the surrounding general public. Therefore, it is essential to have a training simulator which is capable of simulating the phenomena and the response of the RMS during various circumstances such as steady state operation, iodine and cesium peaking after a rapid shutdown and release of large quantity of fissior products into the primary system, secondary system and containment following a severe accident.

2. MODEL DESCRIPTION

The model consists of three major portions including source module, primary side curie transport module and BOP system transport module.

Source Module

Normal Condition: Under normal operating conditions, the radiation source normally come from the fission products of the fuel and the nuclear activation in the nuclear structure and its corrosive products(Sowden 1963). The radioactive fission products are normally confined in the fuel cladding. Some very trace amount of these isotopes may leak into the reactor coolant (Cohen 1980).

<u>Abnormal Conditions</u>: For abnormal conditions such as clad or core damage due to high temperature, the amount of activity release can increase the RCS coolant radiation level thousands of times higher than normal. The model uses NRC's NUREG 0737 Criterion 2(a) as the guideline regarding the initial estimate of the degree of reactor core damage.

The model permits 4 damage classes and 3 degrees of damage which result in 10 release categories as shown in Table 1 (Shoua 1983).

The categories or release are determined by the core pressure and temperature (in-core T/C's) curve as shown in Fig. 1 (B&W, 1970). Reactor Coolant System (RCS) pressure/temperature coordinates to the left of curve B represents "normal" RCS activity.

The region between curve B and curve C indicates potential for cladding failure and release to the RCS coolant of noble and volatile fission product gases contained in the gap formed by the fuel pellet and cladding. The curve D represents clad temperatures in excess of 2300 degree F. The region between curves C and D indicates the potential for fuel overheat and the release to the RCS coolant of noble and volatile fission product gases contained in the core fuel matrix.

The curve E in the Figure 1 represents cladding temperature in excess of 2800 degree F. It is assumed that in this region nongaseous fission products contained in the fuel gap and fuel matrix will be released.

The regions between all curves will be broken down into three distinct sub-regions. Each sub-region will represent an NRC damage classification. The regions together with the NRC damage code classification and fraction released are also illustrated in Figure 1.

The category 1 is corresponding to NRC's Class 1, categories 2 through 4 are for class 2, categories 5-7 for class 3 and categories 8-10 for class 4.

Primary Side Curie Transport

The transport model is embedded in the RCS model which simulates the ! nuclide conservation, decay and transport in every fluid node of the primary system flow paths. Two 💬 additional activity balance equations are implemented to simulate " rapid increase in the iodine and cesium activities following rapid power changes such as reactor trip ... (Makenna, 1988). It also determines the nuclide transport to the other balance-of-plant systems such as Makeup or Decay Heat Removal System and the leakage of the radioactive nuclides into the secondary systems in the event of steam generator tube rupture which can be activated by Instructor Station

through specific Malfunction tableau.

The modified model considers the following activity transport process:

- Transport of the activated material and fission products from fuel to the primary coolant (Makenna, 1988),
- Radiactive nuclide accumulation due to continuous release, and removal due to purification and decay (Makenna, 1988),
- Activity transport in water or in steam from primary side system to secondary system through steam generator tube rupture (Beahm, 1989).

BOP Curie Transport

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The BOP systems that are to be considered in this stage of modification are limited to the pathways and components directly related to the radioactive material transport during a Steam Generator Tube Break. Conservation equations for radioactive material are implemented in every fluid node along main steam system to the condenser, and reactor building in case of Loss of Coolant Accident. Activity removal mechanism, including decay, dilution and being transported out of system, are also simulated.

3. PERFORMANCE TESTS AND RESULTS

Many tests are performed on the TMI plant reference simulator to verify the model performance against plant radiation monitor's readings.

An example test is discussed to demonstrate the model's capability of simulating rapid increase in the iodine and cesium activities following a reactor trip.

The total OTSG leakage rate is set at 0.03 GPM based on plant data. Before the reactor trip, the simulator was running at full power. Fig. 2 illustrate the behavior of radiation monitor's readings at letdown line taken from Recorder RM-L1.

Figure 2 identifies rapid increases in the iodine and total gamma activities as high as 1-2 orders of magnitude. This is in agreement with the plant data following a reactor trip on 11/29/87.

4. CONCLUSION

Radioactive material transport during normal operation or following a severe transient is a very complex process. In order to properly simulate the Radiation Monitoring System Response, extensive modifications of the current simulator system software are implemented on TMI plant reference simulator. The testing results have indicated that the present RMS model is capable of simulating the actual release, transport and response of the Radiation Monitoring System for steady state and transient operations. In addition, the simulator has also demonstrated that it is consistent with the NUREG-0737 guideline for initial estimate of the degree of core damage for severe accidents and the dose assessment calculations of the plant emergency preparedness model.

5. ACKNOWLEDGEMENT

The authors wish to thank D.J.Boltz, N.D. Brown, W.A. Fraser, F.D. Piazza, and R.A. Washick for their support in preparation of this paper. We also wish to thank our many colleagues who support this modification on TMI simulator.

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Table 1, Degree of Core Damage and Isotope Release

·		C	amage		Degree	
		clad	fuel	gap isotopes	fuel isotopes	rare earths
	1	good	good	-	-	-
	2	bad	good	10%	-	-
	3	bad	good	50%	-	-
	4	bad	good	100%	-	-
	5	bad	overheat	100%	10%	-
·	6	bad	overheat	100%	50%	-
	7	bad	overheat	100%	100%	-
	8	bad	melt	100%	100%	10%
	9	bad	melt	100%	100%	50%
	10	bad	melt	100%	100%	100%

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	٨	8	C	D	E
855	"Mormal" Activity	Release of core fission product noble and volatile gases contained in GAP	Release of core fision product noble and volatile gases contained in fuel matrix	Release of core fission product- non-gases con- tained in the CAP (Code 0) and fuel matrix Code 0, 9 10)	
Pressure (psig)	NRC Code 1	Code 2/Code 3/Code 4 0.1 0.5 1.0	Code 5/Code 6/Code 7/ 0.1 0.5 1.0	Code #/Code 9/Code 10 GAP1 CORI. CORI CORE 0.1 0.5 1.0	
	Saturation	ptA = (RCS Press + 3209)/4.23	ptB =)RCS Press 3209)/4.23	ptC = (RCS Press + 9000)/4.0	ptD = (RCS Press + 9500)/4.0
		TCLAD > 1400	TCLAD > 1000	TCL AD > 2300	TCLAD > 2800

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INCORE T/C Temperature degrees F

Figure 1, Degree of Core Damage Versus RCS pressure and Core Thermocouple or Cladding Temperature.



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2.1 Momentum Equation

For a homogeneous mixture flowing in a constant cross-sectional area duct, the differential momentum equation can be written as follows:

$$\frac{\partial G}{\partial t} + \frac{\partial (G^2/\rho)}{\partial Z} = -\overline{g} \frac{\partial p}{\partial Z} - \frac{\partial F}{\partial Z}$$
(1)

where

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 $G = mass flux, lb_m/(ft^2.s),$ $\rho = mixture density, lb_m/ft^3,$ $\overline{g} = Conversion factor = 32.2 X 144,$ p = pressure, psia F = Fanning friction pressure drop,

and the gravity effects are neglected. For momentum consideration, the pressure is assumed to act at the upstream boundary of the nodes as shown in Figure (1).

Integrating Equation (1) from i to a and assuming uniform G and ρ within this interval, We obtain

$$\frac{dG_{ji}}{dt} = \frac{1}{L_{ji}} \left[\frac{g}{g} (Pi - Pa) - Fia \right]$$

where

G_ji = mass flux in node i, lb_m/(ft².s), L_{ji} = length of node i, ft, Pi = Pressure of node i, psia, Fia = Fanning friction pressure drop between i and a.

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FIGURE 1 CONVENTIONS RELATED TO THE LINK-NODE GEOMETRY

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In the region from a to m, the length is infinitesimally small. It is assumed that the fluid density denoted by ρ_j is constant across this abrupt area change and the expression commonly used for abrupt area change in single phase flow is applicable. That is,

$$(p_m - p_a) \overline{g} = (Kr - K) \frac{G_{ji}^2}{2\rho_{ji}}$$

where

 $p_{m} = pressure in node m, psia,$ $Kr = 1 - \frac{A_{i}}{Am}^{2}, \text{ coefficient which accounts for the reversible part of pressure drop,}$ $A_{i} = flow \text{ area of node } i, ft^{2},$ $Am = flow \text{ area of node } m, ft^{2},$

K = coefficient which accounts for the irreversible part of pressure drop.

Elimination of
$$P_a$$
 from Equations (2) and (3) yields

$$\frac{dG_{ji}}{dt} = \frac{1}{L_{ji}} \left[\overline{g} \left(Pi - Pm \right) - Fia + \left(Kr - K \right) \frac{G_{ji}^2}{2\rho_j} \right]$$
(4)

Assuming

Fia =
$$(f\frac{L}{D})_{ji} = \frac{|\frac{G_{ji}|}{2\rho_i}|_{ji}}{\frac{G_{ji}}{D}} = hydraulic diameter}$$

 $\rho_i = \rho_j$

•••

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and adding a term $(Kj_1 + Kj_2) |G_{ji}|G_{ji}/(2 \rho i)$, to account for the loss other than those due to abrupt area changes between two adjacent nodes and Fanning friction, Equation (4) becomes

$$\frac{dG_{ji}}{dt} = \frac{1}{L_{ji}} \begin{cases} \overline{g} (Pi - Pm) \\ - \left[\left(f \frac{L}{D}\right)_{ji} + K_{j1} + K_{j2} \right] \left| \frac{G_{ji}}{2\rho_i} \right|^G G_{ji} \\ + \left[\left[1 - \left(\frac{Ai}{Am}\right)^2 \right] - K \right] \left| \frac{G_{ji}}{2\rho_i} \right|^2 \end{cases}$$
(5)

= ∆P

In the numerical integration of Equation (5), a first order explicit scheme is used. That is,

$$G_{ji}^{n+1} = G_{ji}^{n} + \Delta G_{ji}$$
(6)

where

 $\Delta G_{ji} = \Delta t^{\cdot} \Delta P$ n = index for time sequence, Δt = time step, S.

The mass flux G_{ji}^{n+1} obtained from Equation (6) is then used to calculate the mass and energy transfers between node i and node m as described in the next section.

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G. Radiological Safety, Hazard and Accident Analysis

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See Authorization information

NESC0433 CONTEMPT, LWR CONTAINMENT PRESS & TEMP DISTR IN LOCA 900223

1. NAME OR DESIGNATION OF PROGRAM - CONTEMPT-LT/028, CONTEMPT-LT/026.

2. COMPUTER FOR WHICH PROGRAM IS DESIGNED

Program-name	Package-ID	Orig. Computer	Test Computer
CONTEMPT-CONPS	NESC0433/02	IBM 360 series	IBM 360 series
CONTEMPT-LT	NESC0433/03	IBM 370 series	IBM 370 series
CONTEMPT-LT/28-H	NESC0433/08	IBM 3090	DEC VAX 8810
CONTEMPT-LT026	NESC0433/04	IBM 370 series	IBM 370 series
CONTEMPT-LT26B	NESC0433/01	IBM 370 series	IBM 370 series
CONTEMPT-LT28B	NESC0433/06	CDC 7600	CDC 7600
CONTEMPT-LT28B	NESC0433/07	CDC 7600	CDC_7600
CONTEMPT-PS	NESC0433/05	IBM 360 series	IBM 360 series

3. DESCRIPTION OF PROBLEM OR FUNCTION

CONTEMPT-LT was developed to

predict the long-term behavior of water-cooled nuclear reactor containment systems subjected to postulated loss-of-coolant accident (LOCA) conditions. CONTEMPT-LT calculates the time variation of compartment pressures, temperatures, mass and energy inventories, heat structure temperature distributions, and energy exchange with adjacent compartments. The program is capable of describing the effects of leakage on containment response. Models are provided for fan cooler and cooling spray engineered safety systems. One to four compartments can be modeled, and any compartment except the reactor system may have both a liquid pool region and an air-vapor atmosphere region above the pool. Each region is assumed to have a uniform temperature, but the temperatures of the two regions may be different. The user determines the compartments to be used, specifies input mass and energy additions, defines heat structure and leakage systems, and prescribes the time advancement and output control. CONTEMPT-LT/28-H (NESC0433/08) includes also models for hydrogen combustion.

4. METHOD OF SOLUTION

The initial conditions of the containment atmosphere are calculated from input values, and the initial temperature distributions through the containment structures are determined from the steady-state solution of the heat conduction equations. A time advancement proceeds as follows. The input water and energy rates are evaluated at the midpoint of a time interval and added to the containment system. Pressure suppression, spray system effects, and fan cooler effects are calculated using conditions at the beginning of a time-step. Leakage and heat losses or gains, extrapolated from the last time-step, are added to the containment system. Containment volume pressure and temperature are estimated by solving the mass, volume, and energy balance equations. Using these results as boundary conditions, the heat conduction

NESC0433 CONTEMPT, LWR CONTAINMENT PRESS & TE...

equations describing structure behavior are advanced using an implicit technique. The resulting heat transfer rates are used to correct the previous estimates of the water and energy storage in the containment volume, and the containment conditions are obtained by solving for the second time the containment balance equations. The pressure suppression routines use the conditions at the beginning of a time-step to calculate both the initial explusion of water from the vents and the flow through the vents. From the calculated flow rates, mass and energy are removed from the dry well and added to the wet well.

5. RESTRICTIONS ON THE COMPLEXITY OF THE PROBLEM

Maxima of -

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- 20 heat conducting structures
- 101 mesh points for each structure
- 20 regions for each structure
- 50 flow elements in one segment of the horizontal vent pressure suppression system

10 horizontal vents (or branches) in a segment

50 reductions within an input time-step

CONTEMPT-LT can be used for analyzing the transient containment behavior of boiling-water reactors (BWRs) including Mark I, Mark II, and Mark III systems; pressurized-water reactors (PWRs), and experimental water reactor simulators or related experiments.

6. TYPICAL RUNNING TIME

On the CDC 7600, CONTEMPT-LT/028 requires

less than 30 seconds to run the two sample problems. On the IBM 360/ 75, CONTEMPT-LT/026 requires approximately 0.021 second per time advancement with 90 mesh points for heat structures without pressure suppression. The pressure suppression timing is not easily predicted but run time for two sample problems ranges from 0.3 to 2 seconds per time advancement.

CONTEMPT/LT28B (NESC0433/06): NEA-DB executed the test case on CDC 7600 in 70 seconds.

7. UNUSUAL FEATURES OF THE PROGRAM

8. RELATED AND AUXILIARY PROGRAMS

CONTEMPT-LT/028 is the most recent of a series of computer programs developed to describe the thermalhydraulic conditions attendant to Various postulated transients in the containment of light-water reactor systems. CONTEMPT-LT/026 replaced CONTEMPT (NESC Abstract 297), CONTEMPT-CONPS, CONTEMPT-PS, CONTEMPT-LT/022, and CONTEMPT-LT/025 (which contained known errors and was never distributed by NESC).

9. STATUS

NESC0433/02	: Arrived at NEAD	в		
	: in preparation	in preparation		
	: Obsolete			
NESC0433/03	: Arrived at NEAD	В		

NESC0433 CONTEMPT, LWR CONTAINMENT PRESS & TE...

	: in preparation
NESC0433/09	: Boguested by NEADB
NEBC0435700	· Arrived at NFADR
	. Allived at NEADD
	: In preparation
	: Screened
NESC0433/04	: Arrived at NEADB
	: Obsolete
NESC0433/01	: Arrived at NEADB
	: Tested at NEADB
	: Obsolete
NESC0433/06	: Requested by NEADB
	: Arrived at NEADB
	: in preparation
	: Tested at NEADB
	: Obsolete
NESC0433/07	: Requested by NEADB
	: Arrived at NEADB
	: Screened
NESC0433/05	: Arrived at NEADB
	: Obsolete

10. REFERENCES

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Properties of Water,
ANCR Note, 1975.
NRTS Environmental Subroutine Manual,
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Fan Cooler Containment Model in CONTEMPT-LT/025, SPD-25-76 Nevember 1975
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Version 26 Modifications to the CONTEMPT-LT Program
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NESC0433/02 :
NESC0433/03 :
NESC0433/08 :
- Don W. Hargroves et al.:
CONTEMPT-LT/028 - A Computer Program for Predicting Containment
Pressure-Temperature Response to a Loss-of-Coolant Accident
NUREG/CR-0255 TREE-1279 R4 (March 1979).
- NESC Note 81-30 (December 18, 1980)
- D. COLOMDO: Medifications to the Code CONTEMPT IT/20 and Trajerostation of
Models for Hydrogen Combustion
MTC/FL53/86 (April 1986) Preliminary copy (in Italian)
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  System
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NESC0433/04
NESC0433/01
NESC0433/06
              :
 - Don W. Hargroves et al.:
    CONTEMPT-LT/028 - A Computer Program for Predicting Containment
    Pressure-Temperature Response to a Loss-of-Coolant Accident.
   NUREG/CR-0255 TREE-1279 R4 (March 1979).
   NESC Note 81-30 (December 18, 1980).
NESC0433/07
 - NESC Note 81-30 (December 18, 1980)
   Don W. Hargroves et al.:
   CONTEMPT-LT/028 - A Computer Program for Predicting Containment
    Pressure-Temperature Response to a Loss-of-Coolant Accident.
    NUREG/CR-0255 TREE-1279 R4 (March 1979).
NESC0433/05
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11. MACHINE REQUIREMENTS - CONTEMPT-LT26

430 kbytes and a CALCOMP or -SC4060 plotter for graphical output. CONTEMPT/LT28B (NESC0433/06): To execute the sample case on CDC 7600 storage requirements are: 160,000 octal words (SCM) 100,000 octal words (LCM). plotter (CONTEMPT-LT/029); 430K bytes and a Calcomp or SC4060 plotter for graphical output (CONTEMPT-LT/026).

12. PROGRAMMING LANGUAGE USED

NESC0433/02	:	FORTRAN+ASSEMBLER
NESC0433/03	:	FORTRAN-IV
NESC0433/08	:	FORTRAN+ASSEMBLER
NESC0433/04	:	FORTRAN-IV
NESC0433/01	:	FORTRAN+ASSEMBLER
NESC0433/06	:	FORTRAN-IV
NESC0433/07	:	FORTRAN-IV
NESC0433/05	:	FORTRAN-IV

13. OPERATING SYSTEM UNDER WHICH PROGRAM IS EXECUTED

2.1 (CDC SCOPE 7600), OS/360 MVT (IBM360), MVS/XA (IBM).

14. OTHER PROGRAMMING OR OPERATING INFORMATION OR RESTRICTIONS

The

thermodynamic properties of water and steam required by the program are generated by the STH20 program and made available as a library data set.

15. NAME AND ESTABLISHMENT OF AUTHOR - Contributed by

NESC0433 CONTEMPT, LWR CONTAINMENT PRESS & TE...

CDC 7600	D.W. Hargroves, L.J. Metcalfe, and Teh-Chin Cheng* EG&G Idaho, Inc. P.O. Box 1625 Idaho Falls, Idaho 83415
IBM 360	L.L. Wheat and W.J. Mings Idaho National Engineering Laboratory EG&G Idaho, Inc. P.O. Box 1625 Idaho Falls, Idaho 83415
CONTEMPT-LT/28H	E.N.E.L. Thermal and Nuclear Research Center PISA (Italy)
* Contact	

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16. MATERIAL AVAILABLE

NESC0433/02 :

Report:		
INFORMATION	0	records
SOURCE PROG.+DD CARDS+SAMPLE PROBLEMS	0	records
PRINTED OUTPUT OF THE FIRST SAMPLE PROB.	0	records
NESC0433/03 :		
Report:	_	
SOURCE PROGRAM (F4)	0	records
ENVIRONMENTAL SUBROUTINES (F4)	0	records
ENVIRONMENTAL SUBROUTINES (ASS)	0	records
PLOTTING ROUTINE PLAS (F4)	. 0	records
OVERLAY CARDS	0	records
SAMPLE PROBLEM DATA	0	records
SAMPLE PROBLEM PRINTED OUTPUT	0	records
NESC0433/08 :		
CONTEMPT-LT/28-H Information File		
FORTRAN Routines		
ASSEMBLER Routines		
CONTEMPT Binary Steam Table		
JCL to create Load Module		
JCL to run Sample Problem		
S. P. Input CASE1 (BWR) without Hydrogen		
S. P. Input CASE2 (PWR) without Hydrogen		
S. P. Input CASE3 (BWR) with Hydrogen		
S. P. Input CASE4 (PWR) with Hydrogen		
S. P. Output CASE1 (BWR) without Hydrogen		
S. P. Output CASE2 (PWR) without Hydrogen		
S. P. Output CASE3 (BWR) with Hydrogen		
S. P. Output CASE4 (PWR) with Hydrogen		
Report: NUREG/CR-0255 TREE-1279 R4 (March 1979	•)	
Report: MTC/FL53/86 (April 1986) (in Italian)	,	
Report: MTC/SW40/84 (June 1984) (in Italian)		
NESC Note $81=30$ (December 18 1980)		
Information file	55	records
CONTEMPT-LT/28-H FORTRAN SOURCE	15788	records
CONTEMPT-LT/28-H ASSEMBLER source	1209	records
Steam tables (binary for IBM)	0	records
JCL to create load module	26	records

NEA 1368 ARIANNA -2, SUB-COMPARTMENT THERMO-H ...

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See Authorization information

NEA 1368 ARIANNA -2, SUB-COMPARTMENT THERMO-HYDRAULIC TRANSIENTS IN LOCA 931020

1. NAME OR DESIGNATION OF PROGRAM - ARIANNA-2.

2. COMPUTER FOR WHICH PROGRAM IS DESIGNED

Program-name	Package-ID	Orig. Computer	Test Computer
ARIANNA-2	NEA 1368/01	IBM 30xx series	DEC VAX 6000

3. DESCRIPTION OF PROGRAM OR FUNCTION

ARIANNA-2 allows to analyze the behaviour of a thermal-hydraulic transient following a LOCA in a multicompartment containment system during short, medium and long term accidental sequences. The transient is described as a quasisteady state: mass and energy flows, in each time step, are based on the thermodynamic conditions of the previous time step.. The mass and energy inventory in each volume may be modified by the contribution of heat transfer, junction flows and blow-down mass and energy inputs. The flow through the junctions can be evaluated by choosing one of the following three models: Moody, homogeneous inertial flow or orifice polytropic flow. Each control volume can be simulated as a homogeneous steam-water-air mixture or as a stagnant mixture region (atmosphere) above a liquid pool (sumps); the pool region may or may not be in thermodynamic equilibrium with the atmosphere. In the blow-down volumes, isentropic or isenthalpic expansion of the mixture jet is possible together with associated de-entrainment of liquid in the water pool.



energy exchange between volumes, Mass and linked through junctions, are calculated according to the following assumptions:

- inlet and outlet pressures for each junction are equal to those of the two linked volumes;

- thermodynamic flow conditions are equal to those of the donor volume;
- flow properties are constant during the time-step and mixture flow is homogeneous.

The inertial flow is calculated on the basis of a numerical solution of the momentum equation while the orifice flow is calculated on the basis of Moody model (critical case) or ideal gas model. The heat transfer to structures is calculated solving the Fourier equation by a finite difference method; and various options make it possible to calculate heat transfer coefficients.

5. RESTRICTIONS ON THE COMPLEXITY OF THE PROBLEM

ARIANNA-2

program provides up to 100 volumes, 200 junctions, 30 of which can have time-dependent areas, and 100 heat conducting structures which

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NEA 1368 ARIANNA -2, SUB-COMPARTMENT THERMO-H...

can exchange with any combination of compartments or between any compartment and the outside atmosphere. Up to 101 mesh-points for each structure are allowed and up to 20 different material regions.

6. TYPICAL RUNNING TIME

A 2-volumes, 1-junction problem requires 0.005 s per time step of CPU time on IBM 3090. NEA 1368/01: NEA-DB compiled the source program and executed the two test cases included in this package on a DEC VAX-6000 computer in 5m10.54s and 18.36s, respectively.

7. UNUSUAL FEATURES OF THE PROGRAM

The architecture of ARIANNA-2 is completely modular. Additional features such as restart, plotter file automatic time step control permit flexible use of available code features.

8. RELATED AND AUXILIARY PROGRAMS

The ARIANNA-2 is the last in the ARIANNA series of programs originally developed at DCMN of Pisa University.

9. STATUS

NEA 1368/01 : Requested by NEADB : Arrived at NEADB : in preparation

: Tested at NEADB

10. REFERENCES

NEA 1368/01

- N. Cerullo, F. Oriolo and A. Pasculli: ARIANNA-2, Un Nuovo Codice di Calcolo per l'Analisi di Transitori Termoidraulici in Sistemi di Contenimento a Piena Pressione (in Italian) RL 098(84).
- M. Cascioli, N. Cerullo, W. Flospergher, F. Oriolo and S. Paci: Implementazione e Qualifica dei Modelli di Salvaguardia Ingegneristica del Contenimento nel Codice ARIANNA-2 (in Italian) RL 305(87).
- N. Cerullo, A. Mandrefini, F. Oriolo and S. Paci: Validation of the ARIANNA-2 Code on the Basis of HDR V44 and T31.5 Tests
 Second International Conference on Containment Design and Operation

Toronto (October 14/17, 1990).

- N. Cerullo, W. Flospergher, F. Oriolo and A. Pacsulli: A Model for Thermal-Hydraulic Analysis of Transients in PWR Containment Systems the ARIANNA-2 Computer Code Reprint from Energia Nucleare/Anno 2/N. 3 (December 1985).
- NEA Data Bank: Graphical Comparison of the Original IBM Results (full line) with those Obtained on the DEC VAX 6000 (marks)

NEA 1368 ARIANNA -2, SUB-COMPARTMENT THERMO-H...

Page 3 of 4

NEADB (19/10/93).

11. MACHINE REQUIREMENTS

4 MB of memory are needed for compilation and execution on IBM 3090.

12. PROGRAMMING LANGUAGE USED

NEA 1368/01 : FORTRAN-IV

13. OPERATING SYSTEM UNDER WHICH PROGRAM IS EXECUTED

MSV, VM (IBM 370). NEA 1368/01: VAX/VMS V5.5-2 with VAX Fortran-77 compiler.

14. OTHER PROGRAMMING OR OPERATING INFORMATION OR RESTRICTIONS

Numerical output may show system-dependent variations.

15. NAME AND ESTABLISHMENT OF AUTHORS

N. Cerullo, F. Oriolo Dipartimento di Costruzioni Meccaniche e Nucleari Facolta di Ingegneria Via Diotisalvi, 2 - I - 56126 PISA (ITALY) Telefax 39-50-585265, Telex 500104 FINGPI I

16. MATERIAL AVAILABLE

NEA 1368/01 HDR Input File HDR Output File DCMN Input File DCMN Output File ARIANNA Source Program Report: RL 098(84) (in Italian) Report: RL 305(87) (In Italian) DCMN 013(90) (October 14/17, 1990) Reprint from Energia Nucl. (December 1985) NEADB (19/10/93) 190 records ARIANNA-2 information file 3764 records ARIANNA-2 source code 29 records ARIANNA-2 job control for installation 110 records ARIANNA-2 test input file # 1 1892 records ARIANNA-2 test output file # 1 34 records ARIANNA-2 test input file # 2 ARIANNA-2 test output file # 2 2002 records

17. CATEGORY = G, H,